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# INTEGRATED OPTICAL SIGMA-DELTA MODULATORS

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# Integrated optical sigma-delta modulators

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Abstract. Modern avionics equipment, such as superresolution direction-finding systems (frequency band 0.3 to 3 MHz), now require resolutions greater than 15 bits. Oversampled analog-to-digital converter architectures offer a means of exchanging resolution in time for that in amplitude and represent an attractive approach to implementing precision converters without the need for complex precision analog circuits. Using oversampling techniques based on sigma-delta ( $\Sigma\Delta$ ) modulation, a convenient trade-off exists between sampling rate and resolution. One of the major advantages of integrated optics is the capability to efficiently couple wideband signals into the optical domain. Typically,  $\Sigma\Delta$  processors require simple and relatively low precision analog components and thus are well suited to integrated optical implementations. The current  $\Sigma\Delta$  methodology is reviewed and the design of the single-bit, integrated optical  $\Sigma\Delta$  modulator is presented. Simulation results for both first- and second-order architectures are presented by evaluating the transfer characteristics numerically. A 16-bit  $f_0$ =1 MHz design (oversampling ratio of 132) is also quantified. © 1996 Society of Photo-Optical Instrumentation Engineers.

Subject terms: optical analog-to-digital converters; sigma-delta; direction finding systems.

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#### 1 Introduction

Analog-to-digital converters (ADCs) are basic building blocks for a wide variety of digital systems. A partial list of ADC applications includes process control, automatic test equipment, video signal acquisition, audio recordings for compact discs, and interfaces for personal computers. There exists a variety of approaches to the ADC design. One approach, known as delta modulation, involves the use of oversampling methods. First introduced in the 1940s, delta modulation uses oversampling and single-bit code words to represent the analog signals. The simplest approach counted the output bits from the delta modulator with a high bit representing a+1 and a low bit representing a-1. The output was then resampled at the Nyquist rate. Resolution proved to be a problem, since achieving adequate reproduction of speech signals required oversampling ratios of the order 5000. More effective digital filtering was needed to prevent the high-frequency modulation noise from aliasing into the signal band when it was resampled at the Nyquist rate.

Unfortunately at that time, digital filters used for this purpose were prohibitively expensive. Candy proposed an interpolative technique for digital filtering.<sup>2</sup> The idea was to digitize the signal through the use of a coarse quantizer and cause the output to oscillate between the quantized levels at high speed so that its average value over the Nyquist interval was an accurate representation of the sampled value. The digital filters used to generate this average were inexpensive. On the other hand, these digital filters also proved to be reliable and fairly tolerant of circuit imperfections. The quantizers for these interpolating converters utilized a noise-shaping technique that measures the quantization er-

ror in one sample and subtracts it from the next input sample value.<sup>3</sup> The most popular form of this noise-shaping technique is known as sigma-delta  $(\Sigma\Delta)$  modulation. Sigma delta modulators employ integration and feedback in iterative loops to obtain high-resolution analog-to-digital (A/D) conversions.

Specifically, a sigma-delta modulator  $(\Sigma \Delta M)$  consists of an analog filter and a quantizer enclosed in a feedback loop.4 Together with the filter, the feedback loop acts to attenuate the quantization noise at low frequencies while amplifying the high-frequency noise. Since the signal is oversampled at many times the Nyquist rate, a digital lowpass filter can be used to remove the high-frequency quantization/modulation noise without affecting the signal band. This filtering usually involves a multistage decimation process since the output of the modulator represents the signal with the high-frequency modulation noise as well as its out-of-band components, which dominate at the lower frequencies. In general, the smoothing characteristics involved in the decimation process require that the signal propagate through several filters and resampling stages. The first stage of decimation lowers the word rate to an intermediate frequency, where a filter removes the highfrequency modulation noise. A second low-pass filter is then used to attenuate the out-of-band components before the signal is resampled at its Nyquist rate. As the signal propagates through the filters and resampling stages, the word length increases to preserve the resolution. A more thorough discussion of multistage decimation and filtering can be found in Ref. 1.

The transmission of coherent light through optical waveguides has been of great interest ever since the late

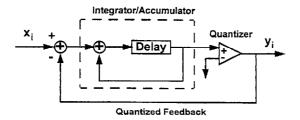


Fig. 1 Block diagram of a first-order all-electronic  $\Sigma \Delta M$ .

1960s. Through this interest emerged the concept of integrated optics, in which wires and radio links are replaced by light-waveguiding optical fibers and conventional electrical integrated circuits are replaced by miniaturized optical integrated circuits (OICs). Optical components offer a number of advantages over their electronic counterparts. These advantages include large bandwidth, use of optical sources capable of high-speed switching [which is necessary for high pulse repetition frequencies (PRFs)], low power consumption, improved reliability, and insensitivity to vibration and electromagnetic interference (EMI). A key advantage is the increased characteristic bandwidth over electronic components. The carrier medium is a lightwave rather than an electrical current. Thus the frequency limiting effects of capacitance and inductance can be avoided. Since electronic converters based on  $\Sigma\Delta$  modulation require oversampling, their applicability is mainly limited to low and moderate signal frequencies. The use of optical integrated components provides an attractive solution to the otherwise bandlimited electronic  $\Sigma\Delta$  architecture. Previous researchers have investigated the use of multiple-quantumwell self-electro-optic effect devices within a bulk-optic error diffusion architecture.<sup>5</sup> A first-order modulator was demonstrated<sup>6</sup> at a sampling frequency of 1 kHz. The extension to a second-order architecture was proposed in Ref. 7. Vibration, thermal instabilities, atmospheric turbulence, and scattering can, however, impose severe problems for these types of free-space processors, eliminating their use on platforms that are mobile or airborne.

This paper describes a single-bit, integrated optical  $\Sigma\Delta M$  approach. In Sec. 2, the all-electronic  $\Sigma\Delta$  modulator is reviewed. Both first- and second-order architectures are discussed. Analysis and simulation results for both the first- and second-order models are presented. In Sec. 3, an integrated optical architecture for a first- and second-order  $\Sigma\Delta$  modulator is introduced. The optical devices used for implementation are explained and compared at a component level to the all-electronic design. Simulation results are presented and analyzed. In Sec. 4, the relationship between oversampling and resolution is detailed and discussed in terms of the modulator SNR. In Sec. 5, a 16-bit,  $f_0$ =1 MHz design (oversampling ratio=132) is described in detail. Finally, issues concerning the current simulation model and future efforts are discussed.

# 2 All-Electronic, Single-Bit ΣΔ Modulators

# 2.1 First-Order $\Sigma \Delta M$

A sampled-data equivalent of a first-order  $\Sigma \Delta M$  is shown in Fig. 1. Because this is a sampled-data circuit, the inte-

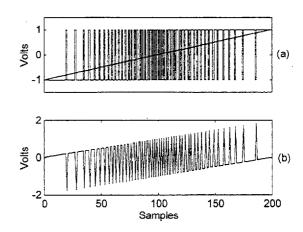


Fig. 2 First-order all-electronic  $\Sigma \Delta M$ : (a) comparator output and sampled input and (b) output of accumulator stage.

gration is performed via an accumulator. The analog signal is assumed to be oversampled at well above the Nyquist frequency. This sampled input  $\mathbf{x}_i$  is fed to the quantizer via the accumulator. The quantized output, which can be modeled as an approximation of the quantization error, is fed back and subtracted from the input. This quantized, feedback signal forces the average value of the quantized output  $\mathbf{y}_i$  to track the average value of the input signal. Any difference accumulates in the integrator and eventually corrects itself.

The quantization error is subtracted from the input value and the difference becomes the input for the next cycle. After the process is repeated many times at high speed, an average of the digital outputs occurring in each sample time becomes a useful digital representation of the input signal. In a stable converter, the oscillations of the quantized value are bounded, that is, it has a limit cycle. In general, this quantization process can be performed over more than one quantization level. By this process, it can be seen that the speed of operation obviates the need for precise circuit elements. Precision in the quantization levels of the quantizer is not a stringent requirement since the average of the quantized output y, will automatically be adjusted to agree with the sampled input analog signal  $x_i$ . Therefore the output of the  $\Sigma\Delta$  modulation process can provide a high level of precision in the representation despite coarseness in the quantization levels.

The input/output transfer characteristics of the first-order  $\Sigma\Delta M$  are plotted in Fig. 2(a). The signal oscillates between the quantized levels in such a manner that its local average equals the average input. For this example the input signal is ramped with 200 samples with a  $\pm 1$  V range. The comparator output voltage is  $\pm 1$  V with the threshold voltage set at 0 V. Figure 2(b) shows the limit cycles at the output of the accumulator. These simulation results are in agreement with previously reported predictions for first-order  $\Sigma\Delta$  modulators. I

#### **2.2** Second-Order $\Sigma \Delta M$

Although the first-order model is the simplest, the quantization noise is highly correlated to the input, resulting in excessive limit cycles. Extending the architecture to a

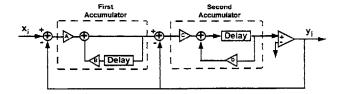


Fig. 3 Block diagram of a second-order all-electronic  $\Sigma \Delta M$ .

second-order modulator eliminates a number of instabilities and increases the reliability of the circuit. However, higher order designs (greater than 2) suffer from instability due to the undesirable limit cycles (bounded oscillations) which result in the accumulation of large signals in the integrators.<sup>4</sup>

A sampled-data equivalent circuit diagram of a secondorder electronic  $\Sigma \Delta M$  is shown in Fig. 3. The first accumulator, which embeds the delay in the feed-backward path, has a transfer function given by

$$H_1(z) = \frac{A}{1 - Bz^{-1}},\tag{1}$$

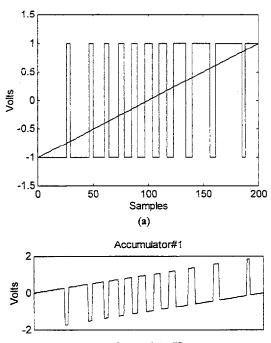
where the coefficients A and B are the gains of the system. The second accumulator stage embeds the delay in the feed-forward path. Its transfer function is given by

$$H_2(z) = \frac{Cz^{-1}}{1 - Dz^{-1}},\tag{2}$$

where coefficients C and D are the loop system gains. For this example all coefficient values are ideally set at unity. As in the first order  $\sum \Delta M$ , the comparator output voltage is  $\pm 1$  volt with the threshold voltage set at zero volts.

The response of the second-order  $\sum \Delta M$  is illustrated in Fig. 4. The input used for simulation consists of 200 data samples ramped from -1 V to +1 V in increments of 0.01 V. The duty cycles of the quantizer output are weighted toward the average value of the input. That is, at the start of the ramped input the duty cycles are weighted toward the bottom-level quantization [Fig. 4(a)]. Toward the center of the input, the duty cycles are at about 50%. At the high end of the ramp, they are weighted toward the top-level quantization. Figure 4(b) shows the signal value at the output of the accumulator stages. From the output of accumulator 1, it can be easily seen that the output is oscillating about the ramped input range of -1 to +1 V. Results of the secondorder modulator illustrate how a second feedback loop attenuates the excessive limit cycles (due to high correlation of the quantization noise) found in the first-order modulator.

Although not part of the current modulator investigation, a decimation filter can then be used to resample the quantized signal at the Nyquist rate. This serves to eliminate any out-of-band quantization noise. It also determines the ratio of the sampled, quantized outputs over the Nyquist interval. This average value proves to be highly representative of the input value.



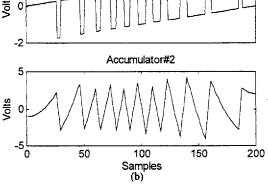


Fig. 4 Second-order all-electronic  $\Sigma\Delta M$ : (a) comparator output and sampled input and (b) input at first and second accumulator stages.

# 3 Integrated-Optical, Single-Bit ΣΔ Modulators

# 3.1 First-Order $\Sigma \Delta M$

A block diagram of a first-order integrated optical  $\Sigma \Delta M$  is shown in Fig. 5. In applying optical integrated components to a  $\Sigma \Delta$  architecture, a first-order model is first simulated. In the integrated optical design, laser pulses from a modelocked laser are used to oversample the rf signal. To gain a better understanding of the model, the integrated optical components used are described in detail.

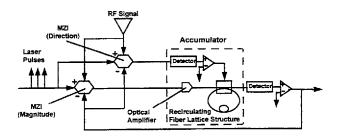


Fig. 5 Block diagram of a first-order integrated optical  $\Sigma \Delta M$ .

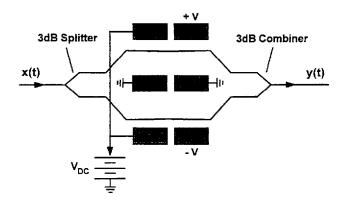


Fig. 6 Schematic diagram of an MZI in a push-pull configuration.

#### 3.1.1 Mach-Zehnder interferometer

The Mach-Zehnder interferometer (MZI) is used to efficiently couple the wideband rf signal into the optical domain. It also serves to subtract the feedback signal from the input signal. Figure 6 shows a schematic diagram of an MZI. The input pulse is split into equal components, each of which propagates over one arm of the interferometer. The optical paths of the two arms are equal. If no phase shift is introduced between the interferometer arms, the two components combine in phase at the output and continue to propagate undiminished. For the current design, a threeelectrode configuration is used to achieve a push-pull phase change. The push-pull effect increases the phase change efficiency of the device. This configuration is utilized to subtract the feedback signal from the next input value. To take advantage of this push-pull configuration, the feedback voltage polarity from the comparator must be reversed. The transfer function of the MZI can be expressed as

$$I_{\text{out}} = I_{\text{in}} \left\{ \frac{1}{2} + \frac{1}{2} \cos \left[ \Delta \phi(\nu) + \theta \right] \right\}$$
 (3)

where

$$\Delta \phi(\nu) = \frac{2\pi n_e^3 r \Gamma L_i \nu}{G\lambda} \tag{4}$$

is the voltage-dependent phase shift and is a function of the effective index of the optical guide  $n_e$ , the pertinent electro-optic coefficient r, the interelectrode gap G, the electrical-optical overlap parameter  $\Gamma$ , and the free-space optical wavelength  $\lambda$ . The modulation voltage,  $\nu = V_{\rm rf} - V_{\rm FB}$ , serves to subtract the feedback signal from the next input value.

The method of accumulation involves the magnitude of the signal to be accumulated and the direction of accumulation. In the case of the first-order  $\Sigma \Delta M$ , two interferometers are used for the accumulator stage. One interferometer provides the magnitude for the accumulator. The other interferometer is used to determine the direction of accumulation. Figure 7 plots the transfer functions for both interferometers. Both MZIs map the input signal to an output intensity between 0 and 1 (light intensity cannot be negative). The transfer functions are the same except for the dc bias  $\theta$ , which is added to the phase shift. For the MZI

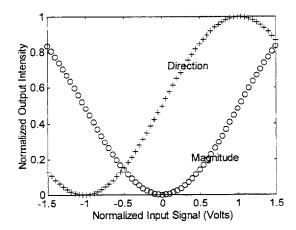


Fig. 7 Transfer characteristic of the MZI.

controlling the magnitude of the signal,  $\theta = \pi$ . The MZI controlling the direction of accumulation has  $\theta = -\pi/2$ .

From the transfer functions, the output values for magnitude range from 0 to 0.5 and are symmetric about the input value of zero. The output values for the direction range from 0 to 1. The accumulator comparator threshold voltage is normalized at 0.5 volts. The detected direction intensity from the MZI is compared to the normalized threshold to determine whether the intensity from the magnitude MZI accumulates upward or downward. The recirculating fiber lattice structure accumulates downward if the output of the interferometer is less than 0.5 and upward for values greater than 0.5. Thus the detector, comparator and optical recirculator serve to function as an accumulator.

# 3.1.2 Fiber lattice structures

Fiber optic lattice structures incorporating single-mode fibers and directional couplers are used to instrument the accumulators. These fiber structures can be used to perform various frequency-domain functions such as matrix operations and frequency filtering.  $^{10}$  Two structures basic to fiber signal processing include the two-coupler nonrecirculating and the two-coupler recirculating delay lines. For design of the optical  $\Sigma\Delta$  modulator, a recirculating feed-backward fiber lattice structure is utilized for the accumulator. The generalized form of a two-coupler, 4-port recirculating fiber delay line is shown in Fig. 8. Moslehi et al.  $^{10}$  described the

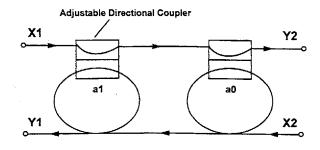


Fig. 8 Block diagram of a recirculating fiber optic lattice structure.

z-transform transfer matrix of this recursive structure. The inputs and outputs are related to each other by

$$\begin{bmatrix} Y_1(z) \\ Y_2(z) \end{bmatrix} = \begin{bmatrix} H_{11}(z) & H_{12}(z) \\ H_{21}(z) & H_{22}(z) \end{bmatrix} \begin{bmatrix} X_1(z) \\ X_2(z) \end{bmatrix}.$$
 (5)

The transfer functions within the transfer matrix are

$$H_{11}(z) = \frac{a_1 - (1 - 2a_1)a_0L_1z^{-1}}{1 - a_1a_0L_1z^{-1}},\tag{6}$$

$$H_{21}(z) = \frac{1}{1 - a_0 a_1 L_1 z^{-1}},\tag{7}$$

$$H_{12}(z) = \left[ (1 - 2a_0 - 2a_1 + 4a_0a_1 + a_0^2a_1^2 + a_0^2 - 2a_0^2a_1 + a_1^2 - 2a_1^2a_0)L_1z^{-1} \right] / (1 - a_0a_1L_1z^{-1}),$$
 (8)

$$H_{22}(z) = \frac{-a_0 - a_1(1 - 2a_0)L_1 z^{-1}}{1 - a_1 a_0 L_1 z^{-1}},$$
(9)

and describe the use of the general structure, where  $H_{mn}(z)$  is the transfer function from input  $X_n$  to output  $Y_m$ . Thus  $H_{21}(z)$  relates the  $X_1$  input and  $Y_2$  output and  $H_{12}(z)$  relates the  $X_2$  input and  $Y_1$  output. The parameters  $a_0$  and  $a_1$  are the intensity coupling coefficients of the directional couplers and  $L_1$  is the loop intensity transmittance of the system. For convenience,  $L_1$  is assumed to be 1 (no losses in the system). The accumulator comparator voltage is then used to bias the directional coupler  $a_1$  to create a phase change between the two pulses to perform the accumulation.

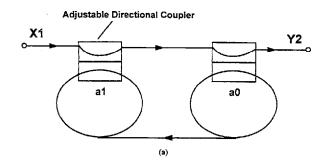
The accumulator stage in the first-order model has a transfer function given by Eq. (2). From the transfer matrix of the recirculating fiber lattice structure,  $H_{12}(z)$  matches this form, where

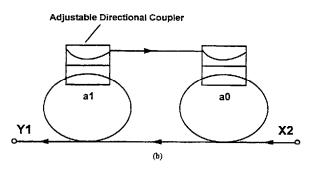
$$C = 1 - 2a_0 - 2a_1 + 4a_0a_1 + a_0^2a_1^2 + a_0^2 - 2a_0^2a_1 + a_1^2$$
$$-2a_1^2a_0 \tag{10}$$

and

$$D = a_0 a_1 \tag{11}$$

are the corresponding gain values. The specific lattice configuration is shown in Fig. 9(b). The coupling coefficients  $a_0$  and  $a_1$  represent the percentage of light intensity coupled and therefore bounded between 0 and 1. The desired values for C and D would be unity. However, the two equations work against each other simultaneously as shown in Fig. 10. Here  $a_0$ =0.3 and  $a_1$  varies from 0 to 1. Values near the intersection of C and D provide the best results  $(a_1$ =0.5, C=0.122, D=0.15). To compensate for the small value of C, an optical amplifier with a gain of 100 is placed just prior to the fiber lattice structure in the accumulator stage (see Fig. 5). Figure 11 plots the transfer characteristic of the first-order integrated optical  $\Sigma \Delta M$ . It is apparent that the first-order system is not stable enough for accurate conversion of the signal due to excessive limit cycles.



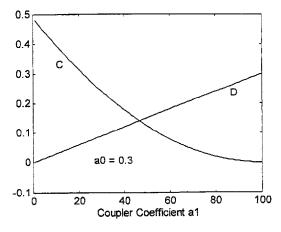


**Fig. 9** Block diagrams of specific fiber lattice configurations used for electro-optic  $\Sigma \Delta M$ : (a) first accumulator stage with transfer function  $H_{21}(z)$  and (b) second accumulator stage with transfer function  $H_{12}(z)$ .

#### **3.2** Second-Order $\Sigma \Delta M$

The block diagram for a second-order integrated optical  $\Sigma \Delta M$  is shown in Fig. 12. The specific fiber lattice structure configurations used for the two accumulator stages are shown in Fig. 9. The first stage (accumulator 1) has the transfer function described by Eq. (1) and uses  $H_{21}(z)$  given by Eq. (7). The coupler coefficients are set ideally at unity, thus the gains A and B are also set at unity. The second stage (accumulator 2) is identical to the accumulator stage in the first-order  $\Sigma \Delta M$ . The coupler coefficients are again  $a_0$ =0.3 and  $a_1$ =0.5 and the gain of the optical amplifier is now 15.

Simulation results for the second-order integrated optical  $\Sigma \Delta M$  are plotted in Fig. 13. The average value of the



**Fig. 10** Plot of accumulator gains C and D as functions of  $a_0$  and  $a_1$ .

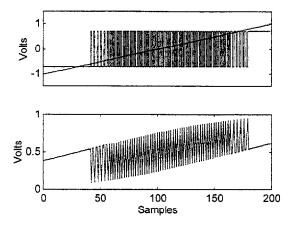


Fig. 11 Transfer characteristic of first-order electro-optic  $\Sigma \Delta M$ .

quantizer output can be seen to track the average value of the ramped input, as shown in Fig. 13(a). The output of the interferometer can be seen to oscillate about the ramped input. Figure 13(b) plots the intermediate signal values at the input of the MZIs in the accumulator stages. These results compare favorably to those of the all-electronic design and demonstrate the feasibility of the integrated optical approach.

# 4 Oversampling Ratio and Resolution

The quantization utilized in  $\Sigma \Delta M$  introduces noise in the modulator. The quantization error e is treated as white noise having probability of lying anywhere in the range  $\pm \Delta/2$ , where  $\Delta$  is the level spacing (normalized units) between quantized levels. Its mean-square value is given by  $\Delta = \Delta/2$ .

$$e_{\rm rms}^2 = \frac{1}{\Delta} \int_{-\Delta/2}^{+\Delta/2} e^2 de = \frac{\Delta^2}{12}.$$
 (12)

The oversampling ratio (OSR), defined as the ratio of the sampling frequency  $f_s$  to the Nyquist rate  $2 f_0$ , is given by the integer

$$OSR = \frac{f_s}{2f_0} = \frac{1}{2f_0\tau}.$$
 (13)

The noise power in the signal band can be shown to be

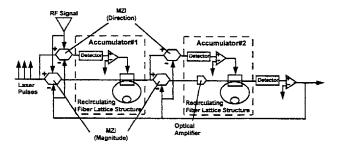
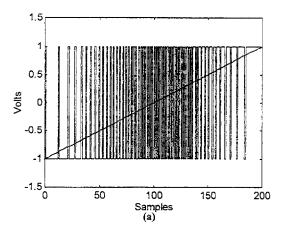


Fig. 12 Block diagram of second-order electro-optic  $\Sigma \Delta M$ .



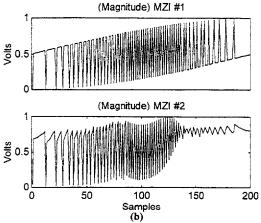


Fig. 13 Transfer characteristic of a second-order electro-optic  $\Sigma \Delta M$ : (a) 200 input sampled-data values versus the output and (b) outputs at first and second accumulator stages.

$$n_0^2 = \int_0^{f_0} e^2(f) df = e_{\text{rms}}^2(2 f_0 \tau) = \frac{e_{\text{rms}}^2}{\text{OSR}}.$$
 (14)

It is evident that oversampling reduces the in-band root-mean-square (rms) quantization noise  $n_0$  by the square root of the OSR.

The feedback loops in the  $\Sigma \Delta M$  help shape the spectrum of the modulation noise by moving most of the noise outside the signal band. The filters used in the loops reduce the net noise in the signal band. The  $\Sigma \Delta M$  subtracts the previous value of the quantization error from the present error. In the case of two feedback loops, the modulation noise becomes the second difference of the quantization error. The SNR for a second-order  $\Sigma \Delta M$  can be predicted from  $\Gamma$ 

$$\frac{n_0}{\Delta} = \frac{\pi^2}{\sqrt{60}} (\text{OSR})^{-5/2}.$$
 (15)

For a second-order  $\Sigma \Delta M$ , the SNR increases at 15 dB/octave and 6 dB/bit. Thus for OSR=128 and  $\Delta$ =2, and

 $n_0$ =-97 dB. For a signal strength of 1 (i.e., 0 dB), SNR=- $n_0$ =97 dB. At 6 dB/bit, this translates to 16 bits of resolution.

# 5 16-Bit Second-Order Example

In this section, the design of a 16-bit,  $f_0$ =1 MHz, second-order device is detailed. There are three fundamental limitations associated with digitizing wideband signals: sample time fluctuation, interaction time (laser pulse width), and thermal noise. These limitations limit the bit resolution B of the A to D process. It has been shown, in terms of the bit resolution and the maximum frequency to be digitized, that the jitter  $\delta t$  satisfies<sup>11</sup>

$$\delta t < \frac{1}{2^{B+1} \pi f_{\text{max}}}.\tag{16}$$

Similarly, the pulse width,  $\Delta t$  satisfies

$$\Delta t < \frac{(3/2^{B-1})^{1/2}}{\pi f_{\text{max}}}.\tag{17}$$

For the condition that sampling is performed at the Nyquist rate, i.e.,  $f_{\rm SN}=2\,f_{\rm max}$ , the corresponding effects on the bit resolution, from Eq. (16), is

$$B = \frac{\log_{10}[2/(\pi f_{SN}\delta t)]}{\log_{10}(2)} - 1 = -k - \sqrt{\pi f_{SN}\delta t}$$
(18)

and from Eq. (17),

$$B = \frac{\log_{10}[\sqrt{12}/(\Delta t \pi f_{SN})]^2}{\log_{10}(2)} + 1.$$
 (19)

Equations (18) and (19) are shown plotted versus the Nyquist sampling frequency in Fig. 14 for  $\delta t = 2.4$  ps,  $\Delta t = 3$  ns and  $\delta t = 0.2$  ps,  $\Delta t = 100$  ps. These values correspond to our 16-bit example, and the capabilities of today's commercial off-the-shelf mode-locked lasers, respectively.

To demonstrate the limitation created by thermal noise, a thermal noise power<sup>12</sup>

$$P_n = 4kT f_{\text{max}} \tag{20}$$

is assumed. The ratio of signal power across a reference resistor R to noise power can then be evaluated according to

$$\left(\frac{S}{N}\right)_{\rm dB} = 10 \log \frac{\langle V^2 \rangle}{RP_n}.$$
 (21)

After taking a reference voltage with unity rms and a reference load resistance of  $R = 50 \Omega$ , it follows after letting <sup>13</sup>

$$\left(\frac{S}{N}\right)_{AB} = 6B + 2\tag{22}$$

that

$$B = \frac{1}{6} \left[ 10 \log \left( \frac{1}{100kTf_{SN}} \right) - 2 \right], \tag{23}$$

where again we have taken  $f_{\rm max} = f_{\rm SN}/2$ . For purposes of comparison, Eq. (23) is also plotted in Fig. 14. For any given system, the bit resolution is limited by the effect (thermal, jitter, interaction time) that has the lowest value in Fig. 14. For our example, a 1-MHz signal having a Nyquist rate of 2 MHz can be digitized with 16 bits of resolution as long as the jitter  $\leq$ 2.4 ps, and the pulse width is  $\leq$ 3 ns. Since the guidelines, Eqs. (16) and (17), are fundamentally only dependent on the bandwidth (BW) of the signal being sampled, the jitter and interaction time limitations can be extracted from Fig. 14 for the  $\Sigma-\Delta$  design.

For second-order  $\Sigma - \Delta$  designs it is well known that the OSR must satisfy

$$OSR = \left[ \frac{\sqrt{15}}{\pi^2} 10^{-(6B+2)/20} \right]^{-0.4}.$$
 (24)

For B=16, an oversampling ratio of 132 results. Therefore, the pulses from the sampling laser must have a pulse repetition frequency of  $f_s=264$  MHz. The other significant specifications are obtained from Fig. 14. Note that these requirements are well within the capabilities of commercial off-the-shelf lasers.

A further consideration in the coherent fiber lattice structure is the round trip delay time  $\tau$  of the recirculating lines. Since the constructive/destructive interference (integrate up/integrate down) depends on combining pulses in phase or out of phase, the length of fiber is important. For the 16-bit example,  $\tau=1/f_s=3.8$  ns. In terms of the index of refraction of the single mode fiber n and the speed of light c, the delay time is  $\tau=L(n/c)$  (Ref. 14). With n=1.48, the required length of fiber for a 3.8 ns delay is L=0.77 m.

To compensate for the lattice filter coefficient C=0.122, an erbium-doped fiber amplifier (EDFA) with a gain of 15 is used. This gain value is in the linear region of the EDFA gain versus pump power characteristics (amplifier pumping efficiency), which permit changing the power gain by electronic means. <sup>15</sup>

# 6 Conclusions

The  $\Sigma\Delta$  oversampling A/D modulator architecture uses limit cycles in quantized feedback loops to provide an accurate digital representation of the input signal. The second-order  $\Sigma\Delta M$  provides a stable and robust design that is highly tolerant of circuit imperfections and component mismatch. The major limitations of this method are fast cycle times and bandwidth. The use of fiber optic technology eliminates these limitations. An integrated optical second-order  $\Sigma\Delta$  architecture allows the processing of wideband rf signals. The integrated optical  $\Sigma\Delta M$  design presented in this paper is a fairly straightforward extension of the electronic design using standard integrated optical devices. Current simulation results confirm design feasibility.

Future efforts include further optimization of the current integrated optical design. Modifications may include the possibility of optimizing the magnitude and direction of each accumulation stage using only one interferometer. The

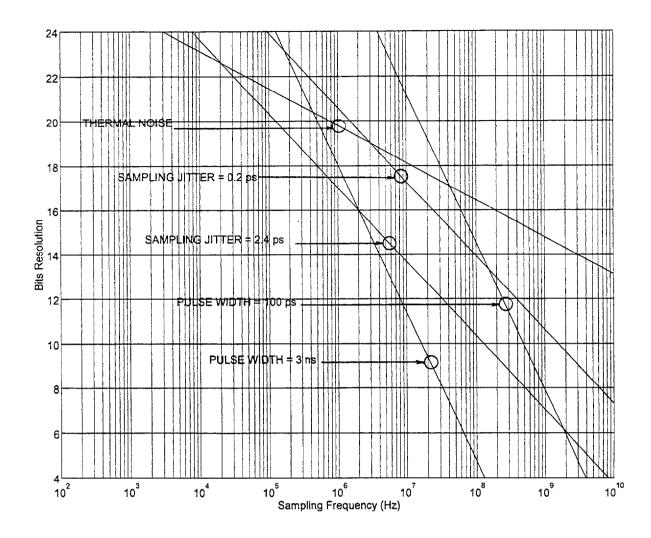


Fig. 14 Fundamental limitations in sampling wideband signals.

accumulation stages of the integrated optical  $\sum \Delta M$  are modeled by fiber lattice structures with similar system transfer functions. More rigorous modeling of these delay line structures and analysis of the optical amplifiers are needed for future hardware implementation. Since the output of the modulator represents the input signal together with modulation noise, there is still a need to decimate the modulated signal. A multistage decimation is needed to lower the word rate and remove high-frequency modulation noise before the signal is resampled at the Nyquist rate. Design issues to be studied include nonlinearities associated with interferometers, stability of the accumulator stages, effects of net gains in the feedback loops, and the effects of modulation noise and oversampling frequency (OSR) on bit resolution.

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